

# The Coordinate System for LDC Detector Studies

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## Abstract

An agreement on a common definition of a global coordinate system for studies of the ILC Large Detector Concept [1] will have various advantages: Simulation tools can be used without adaptation, data can be exchanged without conversion, and results can be compared without re-interpretation. The following document offers such a definition in a concise, yet general way.

## 1 Definition of the Coordinate System

Let  $\vec{p}^-$  and  $\vec{p}^+$  be the nominal three-momenta of the incoming electrons and positrons, respectively. The coordinate system is then defined as follows:

1. The coordinate system is cartesian and right-handed.
2. Its origin is located at the nominal point of interaction.
3. The  $z$ -axis lies along the mean beam direction, pointing such that  $p_z^- > 0$ .
4. The  $y$ -axis lies along the vertical direction, pointing upwards.

The mean beam direction is the bisecting line of the (smaller) angle between  $\vec{p}^-$  and  $\vec{p}^+$ . In the case of a head-on geometry, this angle vanishes and the  $z$ -axis is simply parallel to  $\vec{p}^-$  and antiparallel to  $\vec{p}^+$ . Note that the direction of the  $x$ -axis is already fixed by point 1 in conjunction with points 3 and 4.

## 2 Definition of the Crossing Angle

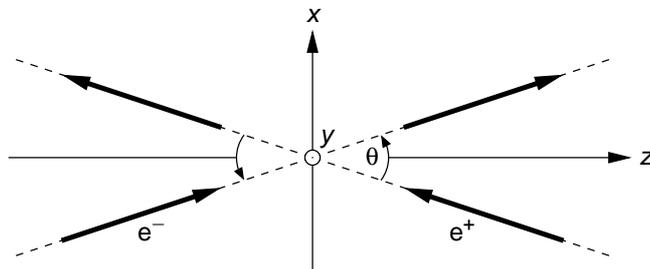
The crossing angle, here denoted by  $\theta$ , is defined as follows:  $\theta \in (-90^\circ, +90^\circ]$  is the angle by which  $\vec{p}^+$  has to be rotated around the  $y$ -axis such that it becomes antiparallel to  $\vec{p}^-$ . If the rotation is right-handed then  $\theta > 0$ , if it is left-handed then  $\theta < 0$ . Note that  $\theta$  will always have the same sign as  $p_x^-$  and  $p_x^+$ .

Even though  $\theta < 0$  must be allowed in order to be able to describe all possible configurations, all studies should use  $\theta \geq 0$  unless there is a special need not to do so. This means that both  $p_x^- \geq 0$  and  $p_x^+ \geq 0$  by default.

Figure 1 shows a top view of a crossing angle geometry with  $\theta > 0$ , taking into account the definitions from sections 1 and 2.

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**Figure 1:** Top view of the coordinate system for a crossing angle geometry with  $\theta > 0$ . The  $y$ -axis is pointing towards the viewer. This should be the default coordinate system for all LDC detector studies.

### 3 Concluding Remarks

The definition presented in this document has already been proposed to the LDC community in the LDC Phone/Video Meeting of 2005-09-29 [2] and has generally been agreed upon. It is compatible to the coordinate system used by Guinea Pig [3] and to the magnetic field maps provided by the SLAC Beam Delivery Group [4].

Guinea Pig simulates, among other things, the  $e^+e^-$  pairs produced by beam-beam interactions for  $p_z^- > 0$ ,  $p_z^+ < 0$ . The field maps stated above provide values for an optional detector-integrated dipole field (DID) with  $B_x < 0$  for  $z > 0$ . This is in agreement with  $p_x^\pm > 0$  for  $\theta > 0$ .

Furthermore, detector geometries which are compliant with figure 1 will soon be available for the major LDC detector simulation programs, “Brahms” [5] and “Mokka” [6].

### References

- [1] LDC Web Site, [www.ilcldc.org](http://www.ilcldc.org)
- [2] LDC Phone/Video Meeting, 2005-09-29, [www.ilcldc.org/meetings/fourthLDCmeetingfolder/](http://www.ilcldc.org/meetings/fourthLDCmeetingfolder/)
- [3] Guinea Pig Web Site, [www-sldnt.slac.stanford.edu/snowmass/Software/GuineaPig/](http://www-sldnt.slac.stanford.edu/snowmass/Software/GuineaPig/)
- [4] SLAC Beam Delivery Meeting, 2005-07-26, [www-project.slac.stanford.edu/lc/bdir/Meetings/beamdelivery/2005-07-26/index.htm](http://www-project.slac.stanford.edu/lc/bdir/Meetings/beamdelivery/2005-07-26/index.htm)
- [5] Brahms Web Site, [www-zeuthen.desy.de/lc\\_repository/detector\\_simulation/dev/BRAHMS/readme.html](http://www-zeuthen.desy.de/lc_repository/detector_simulation/dev/BRAHMS/readme.html)
- [6] Mokka Web Site, [polywww.in2p3.fr/geant4/tesla/www/mokka/mokka.html](http://polywww.in2p3.fr/geant4/tesla/www/mokka/mokka.html)